

FORM PTO-1449

Attorney Docket:	Serial No.:	
1948-4830	10/743,444	
Applicant:	-	
MILGRAM, et al.		
	Group Art Unit:	

		* _ * _ * _		MILC	RAM, et al.						
INFORMATION DISCLOSURE CITATION				Filing Date:		Group Art Unit: 7680	•				
		·	U.S		ENT DOCUMENTS						
Examiner Initial	:	Patent Number	Publica Dat	ation	Name	Class	Sub- Class	Filing Date			
CM	1	5,301,115	04/05/1994		NOUSO	364					
	2	2002/080618 A1	06/27/2002		KOBAYASHI, et al.	362					
V	3	6,459,387 B 1	10/01/2002		KOBAYASHI, et al. 340						
			FORE	IGN P	ATENT DOCUMENTS			<u> </u>			
Examiner Initial		Patent Number	Public Da		Country	Class	Sub- Class	Translation			
CW	1	DE 101 27 324 A1	12/05/2002		German (w/ abstract)		<u> </u>	☐ Yes ⊠ No			
CW	2	EP 1 193 125 A2	09/24/20	001	Europe	V	$\bot \bot \bot$	☐ Yes 🖾 No			
			•				<u> </u>	Yes No			
						·		Yes No			
	·							Yes No			
								Yes No			
					*			Yes No			
					(T. I. dina Author Title	Dota etc.)		L Tes L No			
CW	1	LIN et al. " A Robi Autonomous Syste 19-32, XP 2 (1998)	ust landma ms, Elsevi 19-32.	irk-base ier Scie	(Including Author, Title, d system for vehicle locatine Publishers, Amsterdam	on using low-bandwin, NL, Vol. 25 No.					
	2	and Instrumentatio November 1993.	MASAKI, I. "Three Dimensional Vision System for Intelligent Vehicles" Industrial Electronics, Control, and Instrumentation, 1983. Proceedings of the IECON 1993, International Conference on Maui, HI USA 15-19 November 1993.								
\bigvee	3	DEL BIMBO A, et al. "Dynamic Neural estimation for Autonomous Vehicles Driving" Pattern Recognition, 1992. Vol. II. Conference B: Pattern Recognition Methodology and System, Proceedings, 11 th IAPR International Conference on the Hague, Netherlands 30 August – 2 September 1992 Los Alamitos, CA, USA, IEEE August 30, 1992 Pages 350-354.									
Examiner	•	/Claire Wang/									
EXAMINER:	Draw lin	reference considered, whethe he through citation if not in co copy of this form with next co	nformance a	nd not co	onformance with MPEP §609. nsidered. icant.						